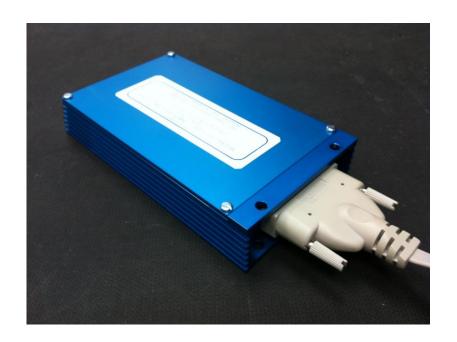


# Documentation for:

# YED/A429R1/NMEAT1/STM32 (NMEA0183) ARINC429 to RS232/RS422 Converter (\$GPRMC, \$GPGGA, \$GPVTG)



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Version 1.2

Documentation for: A429R1-Serial-T1 ~ ARINC429 to RS232/RS422 Converter

# **Amendment Page**

Version	Date of Issue	Change Reference	Remarks
1.0	24 May 2013	N/A	Original Issue
1.1	31 May 2013	N/A	L125 changed to L150. Built-in firmware update Boot Loader. Multiple NMEA 1083 baud rates. Baud rate switch settings.
1.2	21 June 2013	N/A	NMEA 0183 string output content corrected. Explosive decompression data added. LED indicators

Original Author: G.S. Brownett

Date of Origin: 31<sup>st</sup> May 2013

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**Firmware Version:** N/A

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Documentation for: A429R1-RS232T1  $^{\sim}$  ARINC429 to RS232 Converter

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#### 1 Introduction

This manual contains specification data, installation and instructions for the YED/A429R1-Serial-T1/STM32 ARINC-429 Converter.

This converter is in use by many companies who have a requirement to extract navigational data from an ARINC429 data bus and translate it onto an RS232 or RS422 serial data bus. The exact format for the converted data is NMEA 0183 - a marine GPS ASCII format. Depending upon the software version installed, the converter can process a variety of ARINC 429 labels and output a variety of NMEA 0183 message strings. The typical labels processed by this converter are shown in the table below. The converter adapts automatically to high or low speed (12.5/100kHz) ARINC429 data and the inputs are opto-coupled for electrical isolation purposes. The unit is powered from an external 28 VDC (18-72V) nominal supply with internal current and thermal (102 °C) fuse. The power inputs are also reverse polarity protected.

#### 1.1 Software

The software for the YED/A429R1-Serial-T1/STM32 ARINC-429 Converter is written in accordance with RTCA/DO-178B to criticality level E.

This new hardware has a built-in Boot Loader that allows the internal firmware to be updated via RS232. A GUI program downloads the new firmware file to the internal FLASH ROM on the processor thus removing the requirement to return the unit to YED for upgrading.

#### 1.2 Environmental, Airworthiness and EMC

The YED/A429R1-Serial-T1/STM32 ARINC-429 Converter has been designed to meet DO-160D test categories listed later in this manual.

The unit has also been subjected to an Explosive Decompression test from 15,000 feet to 50,000 feet in a period of less than 100mS without effect. See Annex 1.

Documentation for: A429R1-Serial-T1 ~ ARINC429 to RS232/RS422 Converter

# 1.3 Specifications

The YED/Serial-R1-RS485/A429-T1 has the following features: -

#### Physical

The YED/Serial-R1-RS485/A429-T1 attaches to the airframe via four mounting holes. See paragraph titled "Enclosure Outline Drawing" for further details.

Height	28.0mm
Width	68.0mm
Length	136.0mm

Electrical

Reverse polarity protected

ARINC 429 Input Labels

L147 : Magnetic Variation ..... BNR

L150 : UTC (GPS) BNR Hr:Min:S (23:59.59)
L260 : Date (GPS) BCD Dy:Mo:Yr (dd:mm:yr)

L312 : Ground Speed (GPS) ...... BNR Knots

L313 : True Track BNR Degrees (Position Sense CW - N)

L314 : Track Magnetic BNR Degrees (Position Sense CW - N)

L273 : Sensor Status(No. of Sats Tracked) ...... DIS

Serial Output

NMEA 0183, 8 data-bits, 1-Stop, No Parity.

NMEA 0183 messages \$GPRMC, \$GPGGA and \$GPVTG Baud Rates 4800, 9600, 19200, 38400 (other baud

rates available)

NMEA 0183 Update rate...... 1Hz

Environmental

Operating temperature range.....-40 to +85 degrees C.

# 2 Operation

#### 2.1 ARINC429 reception

High or low speed ARINC data is receivable without user intervention. ARINC429 data words must have Odd Parity and the correct SSM (bits 30 & 31) field status otherwise the data will not be included in the serial output data stream.

# 2.2 Serial transmission (NMEA 0183) of received (ARINC 429) data

Serial data will be transmitted at a rate of once per second (1 Hz) and at the specified baud rate. There is no hardware handshake and no parity. Transmitted data is in ASCII format and conforms to NMEA 0183 data format standards. The Sentence header will consist of three ASCII strings "\$GPRMC", "GPGGA" and \$GPRMA. Each line will begin with a '\$' and terminate with a Carriage Return (0x0d) and Line Feed Character (0x0a). The ',' comma delimiters are used to separate each particular parameter field.

#### The various outputs are as follows:-

(i) No ARINC429 data being received:-

```
$GPRMC,,V,,,,,,,*31
$GPGGA,,,,,,,,,M,,M,,*56
$GPVTG,,T,,M,,N,,K*4E
```

The lines show the comma delimiters for each of the missing parameters.

(ii) If all the ARINC429 parameters are being correctly received then the following data will be available at the serial output port:-

```
$GPRMC,121131.00,A,10059.99,N,09000.00,W,190.0,135.0,250113,099.8,E*7C $GPGGA,121131.00,10059.99,N,09000.00,W,,,,03048.0,M,,M,,*45 $GPVTG,100.0,T,135.0,M,190.0,N,351.9,K*4E
```

(iii) The following line shows the UTC time parameter missing. This could be due to the label being unavailable, or the SSM is incorrect, or if the parity is incorrect:-

```
$GPRMC,,V,10059.99,N,09000.00,W,190.0,135.0,250113,099.8,E*44
$GPGGA,,10059.99,N,09000.00,W,,,,03048.0,M,,M,,*6A
$GPVTG,100.0,T,135.0,M,190.0,N,351.9,K*4E
```

(iv) The following lines show the typical output when all parameters are present.

```
$GPRMC,121131.00,A,10059.99,N,09000.00,W,190.0,135.0,250113,099.8,E*7C $GPGGA,121131.00,10059.99,N,09000.00,W,,,,03048.0,M,,M,,*45 $GPVTG,100.0,T,135.0,M,190.0,N,351.9,K*4E {1 second GAP} $GPRMC,121131.00,A,10059.99,N,09000.00,W,190.0,135.0,250113,099.8,E*7C $GPGGA,121131.00,10059.99,N,09000.00,W,,,,03048.0,M,,M,,*45 $GPVTG,100.0,T,135.0,M,190.0,N,351.9,K*4E
```

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.... Etc.

# 2.3 Conversion to the following NMEA 0183 Values:

Time (UTC) hhmmss.ss
Date ddmmyy
Latitude llll.ll
Longitude yyyyy.yy
Track (True) Degrees
Speed over ground knots

Altitude meters (MSL)

Magnetic Variation Degrees

# **Creation of the following NMEA 0183 Strings:**

**Blue** : Fixed constant

Red : From ARINC 429 data

## 2.3.1 The arrangement of the transmitted parameters is as follows for \$GPRMC:-

```
RMC Recommended Minimum Navigation Information
                  2 3 4 5 6 7 8 9
                                        6 7 8 9 10 11 12
| | | | | | | |
                  1 1
                             \$--RMC, hhmmss.ss, A, \verb|lll.ll, a, yyyyy.yy, a, x.x, x.x, xxxx, x.x, a*hh
1) Time (UTC)
2) Status, V = Navigation receiver warning3) Latitude4) N or S
5) Longitude
6) E or W
7)
   Speed over ground, knots
8) Track made good, degrees true
9) Date, ddmmyy10) Magnetic Variation, degrees
11) E or W
12) Checksum
```

The arrangement of the transmitted parameters is as follows (\$GPRMC):-

ARINC	429	Label
1)	150	UTC (GPS)
2)		V or A
3)	310	Present Position Latitude
4)		North South indicator
5)	311	Present Position Longitude
6)		East West indicator
7)	312	Ground Speed (GPS) Knots
8)	314	Course over ground, degrees
9)	260	Date (GPS)
10)	147	Magnetic Variation, degrees
11)		East West indicator
12)		Checksum

#### 2.3.2 The arrangement of the transmitted parameters is as follows for \$GPGGA:-

GGA Global Positioning System Fix Data. Time, Position and fix related data for a GPS receiver

```
3 4
                                    5 67 8 9 1011 121314 15
                         1 1
                                    -GGA, hhmmss.ss, llll.ll, a, yyyyy.yy, a, ,xx, ,x.x, M, , M, , *hh
1) Time (UTC)
2) Latitude3) N or S (North or South)
4) Longitude
5) E or W (East or West)6) GPS Quality Indicator,
      0 - fix not available,
      1 - GPS fix,
      2 - Differential GPS fix
   Number of satellites in view, 00 - 12
8) Horizontal Dilution of precision
9) Antenna Altitude above/below mean-sea-level (geoid)
10) Units of antenna altitude, meters
11) Geoidal separation, the difference between the WGS-84 earth
    ellipsoid and mean-sea-level (geoid), "-" means mean-sea-level below
    ellipsoid.
12) Units of geoidal separation, meters
13) Age of differential GPS data, time in seconds since last SC104
    type 1 or 9 update, null field when DGPS is not used
14) Differential reference station ID, 0000-1023
15) Checksum
```

The arrangement of the transmitted parameters is as follows (\$GPGGA):-

```
ARINC 429 Label

1) 150 UTC (GPS)
```

14)

15)

```
2)
      310
            Present Position Latitude, (GPS)
3)
            North South indicator
4)
      311
             Present Position Longitude, (GPS)
5)
             East West indicator
6)
             -Blank-
7)
      273
            Number of satellite in view
8)
             -Blank-
9)
             GPS Altitude (MSL) convert to meters
10)
             M (meters)
11)
              -Blank-
             M (meters)
12)
13)
             -Blank-
```

-Blank-

Checksum

## 2.3.3 The arrangement of the transmitted parameters is as follows for \$GPVTG:-

### **VTG Track Made Good and Ground Speed**

```
1 2 3 4 5 6 7 8 9

| | | | | | | | | | | | |

$--VTG, x.x, T, x.x, M, x.x, N, x.x, K*hh

1) Track Degrees
2) T = True
3) Track Degrees
4) M = Magnetic
5) Speed Knots
6) N = Knots
7) Speed Kilometers Per Hour
8) K = Kilometres Per Hour
9) Checksum
```

The arrangement of the transmitted parameters is as follows (\$GPVTG):-

#### ARINC 429 Label

```
313
            Track Degrees
      T = True
314 Track Degrees
2)
3)
            M = Magnetic
4)
5)
      312 Speed Knots
6)
             N = Knots
7)
      312
             Speed Kilometers Per Hour
8)
            K = Kilometres Per Hour
9)
             Checksum
```

# 2.4 Baud rate switches.

4800

9600

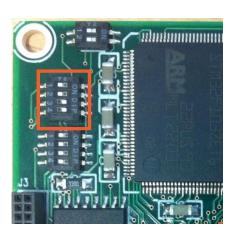




19200

38400





115200

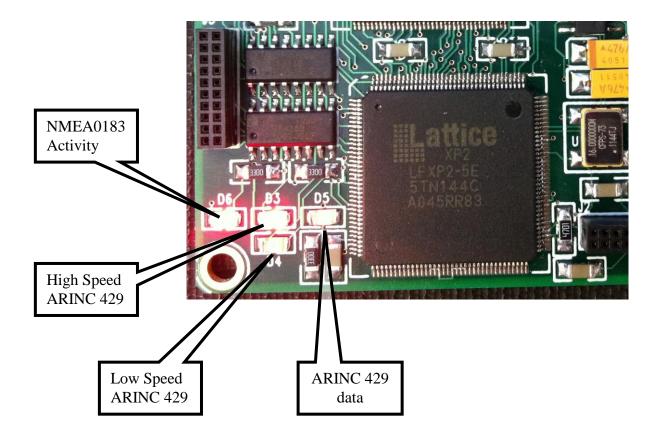


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# 2.5 LED Indicators.



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#### 3 Installation

This section provides details for the installation of the YED/A429R1-Serial-T1/STM32 Converter, including configuration and mounting procedures. Follow the procedures and recommendations found in this section to assure a successful installation.

#### 3.1 Electrical considerations

A circuit breaker such as a Klixon 7277-2-1 or equivalent should be considered for connecting the power from the aircraft supply to this converter – even though the converter is internally fused.

## 3.2 Materials not supplied

• Wire: MIL-W-22759/16 or equivalent

• Shielded wire: MIL-C-27500 or equivalent

• Mounting Screws, 4 each.

## 3.3 Mounting considerations

The YED/A429R1-Serial-T1/STM32 can be mounted in the avionics bay, shelf or other suitable structure. It can be mounted in any orientation.

#### 3.4 Wiring

Use 22 to 24 AWG wire for all connections.

Fabricate wiring harness, and test all wiring for continuity and for shorts. Ensure aircraft power is present on the correct pins of J1; refer to Table 1.

## 3.5 Removal and replacement

## 3.5.1 Removal

- 1. Open the circuit breaker powering the YED P/N YED/A429R1-Serial-T1
- 2. Remove the connector.
- 3. Remove four (4) screws securing the converter to the airframe.

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### 3.5.2 Replacement

- 1. Open the circuit breaker powering the YED/A429R1-Serial-T1/STM32
- 2. Secure the converter to the airframe with four (4) screws.
- 3. Attach the connector and secure
- 4. Close the circuit breaker.
- 5. Perform operational test of the YED/A429R1-Serial-T1/STM32

#### 3.6 Continued Airworthiness

#### 3.6.1 Scheduled Maintenance

Recommended periodic scheduled servicing	None
Recommended periodic scheduled preventative	
maintenance tests	None
Recommended periodic inspections	None
Recommended period overhaul period	None
Special inspection requirements	None
	maintenance tests.  Recommended periodic inspections.  Recommended period overhaul period.

There are no Airworthiness limitations associated with the installation of this converter.

# 4 Environmental & EMC

The YED/A429R1-Serial-T1/STM32 has been designed to meet the environmental test categories detailed below in accordance with RTCA DO-160D, Environmental Conditions and Test Procedure for Airborne Equipment.

Section	Category	Remarks
4.0 Temperature and Altitude	A1, A2	25,000 feet.
5.0 Temperature and variation	B, C	
6.0 Humidity	A	
7.0 Operational Shock and Crash Safety	В	
8.0 Vibration	C,M	
9.0 Explosion Proofness	X	Not tested – See Annex 1
10.0 Waterproofness	X	Not tested
11.0 Fluids susceptibility	X	Not tested
12.0 Sand and Dust	X	Not tested
13.0 Fungus Resistance	X	Not tested
14.0 Salt Spray	X	Not tested
15.0 Magnetic Effect	Z	
16.0 Power Input	A	
17.0 Voltage Spike	В	
18.0 AF Conducted Susceptibility – Power Inputs	A	
19.0 Induced Signal Susceptibility	A, Z	
20.0 Radio Frequency Susceptibility (Radiated and Conducted)	T, V	
21.0 Emission of Radio Frequency Energy	A, Z	
22.0 Lightening Induced Transient Susceptibility	X	Not tested
23.0 Lightening Direct Effects	X	Not tested
24.0 Icing	X	Not tested
25.0 ESD	X	Not tested

# 5 Connector Pin Out (D15 Plug)

The YED/A429R1-Serial-T1/STM32 contains a single 15-pin filtered male connector, J1, per MIL-C-24308.

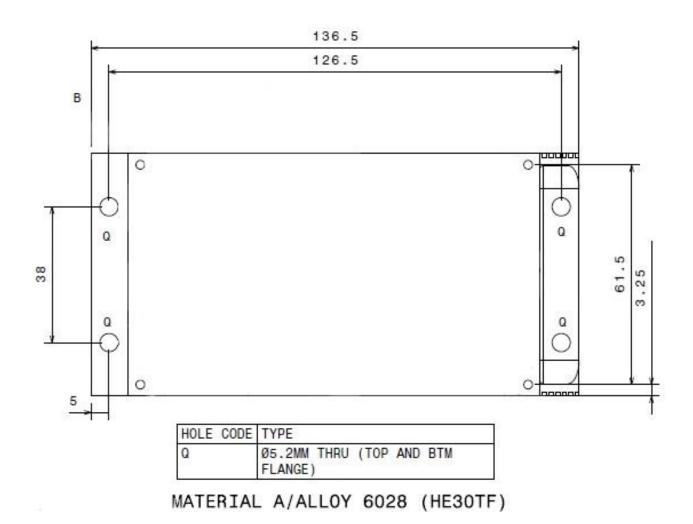


Pin Signal		Function	
1 +28V DC		Primary power	
2	0V Ground	28V DC Return	
3	A429 Tx +Ve	ARINC429 Transmit TXA	
4	A429 Tx -Ve	ARINC429 Transmit TXB	
5	A429 Rx +Ve	ARINC 429 Receive (input) RXA	
6	A429 Rx -Ve	ARINC 429 Receive (input) RXB	
7	A429 Ground (0V)	ARINC 429 Screen	
8	FLASH Enable	Enable reprogram of FLASH ROM code	
9	RS232 Tx Out	RS232 transmitter output	
10 RS232/RS422 Gnd (0V)		RS232 / RS422 Signal/Screen ground	
11	RS232 Rx In	RS232 receiver input	
12	RS422 Tx +Ve Out	RS422 Tx output +Ve	
13	RS422 Tx –Ve Out	RS422 Tx output –Ve	
14	RS422 Rx +Ve In	RS422 Rx input +Ve	
15	RS422 Rx –Ve In	RS422 Rx input -Ve	

Table 1 – J1 Pin Description

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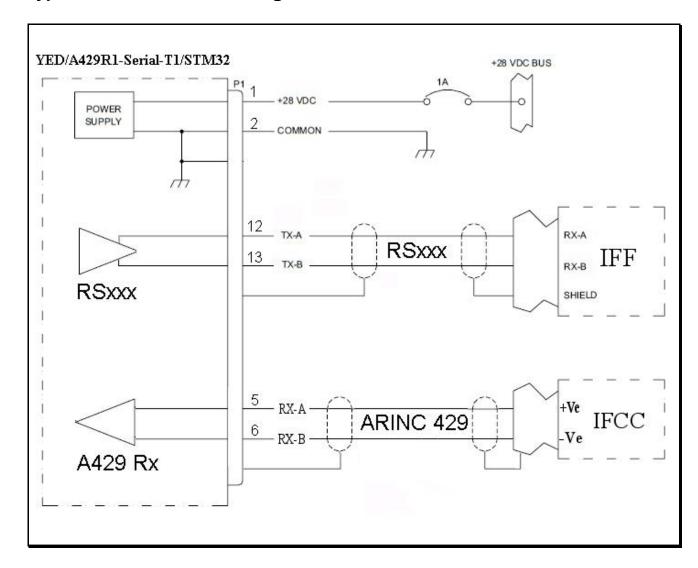
# 6 Enclosure outline drawing



All dimensions are in mm.

Documentation for: A429R1-Serial-T1 ~ ARINC429 to RS232/RS422 Converter

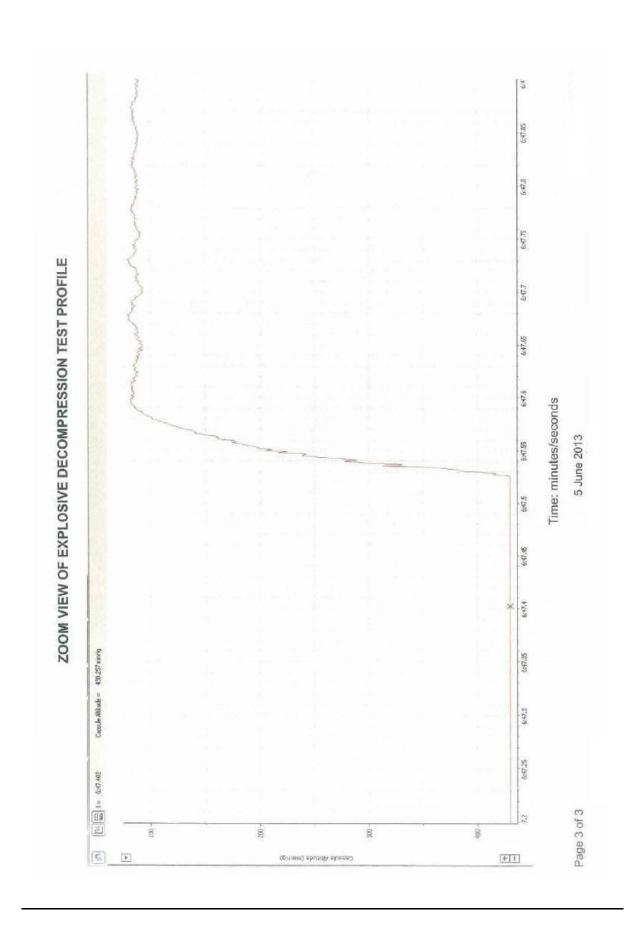
# 7 Typical interconnect drawing



# 8 Annex 1 – Explosion Decompression tests

DECOMPRESSION TESTING OF	NAVIGATION	UNIT
QinetiQ Building 800 Hypobaric Facility (I decompression testing of a Converter unit. The reason for this testing, enable clearance to be given for the equipmen	in conjunction with other require	TACA! ed testing, is t
The equipment to be tested was supplied	on 22 <sup>rd</sup> May 2013 and com	prised:
- YED TACAN Converter unit.	Local Serial N	No. 001.
Prior to the decompression test, the manufacturer had verified to the supplying the equipment that the equipment was serviceable. The equipment did not require to be functioning during the testing and was to be returned to manufacturer for examination post testing.		
The decompression test was carried out in the May 2013 to the following decompression		Building 800) o
<ul> <li>Chamber ascent to 15,000 ft at a rate of Hold for a minimum of 1 minute.</li> <li>Rapid decompression to 50,000 ft (To ratime period).</li> <li>Hold chamber altitude for a minimum of Chamber descent to ground level at 5,000.</li> </ul>	reach 90% of the final altitude with	nin a 0.1-secon
The altitude profile within the chamber was racquisition system. Annex A shows the test p (428 mmHg), explosive decompression to 50 for a minimum of 5 minutes, descent back do level to 15,000 ft and descent from 50,000 ft /min. Annex B shows the actual rapid dechamber reached 90% of the final altitude in a altitude, or pressure, within the chamber are this reason, the pressure recordings show altitude/pressure relationship.	rofile from; ground level (760 mm, 000 ft (87 mmHg) in less than 0 wn to ground level. Chamber asc to ground level was carried out a ecompression in greater detail de 0.05-second time period. The raccontrolled in units of feet per min	Hg) to 15,000 0.1 second, holent from ground that a rate of 5,00 uring which that tes of change oute (ft/min). For
The chamber decompression test proceeded without incident and as far as could be see without any effect on the equipment. The Boscombe Down representative will return the equipment to the manufacturer for examination.		
This documented detail of the testing has bee (Boscomb	n produced by Chas Taylor (Air Doe Down).	livision).

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